

Objective

- Theories on cognitive maps stipulate that hippocampal neural activity is related to the spatiotemporal coding of one's spatial environment.
- We aimed to **decode and determine specific memorized locations and its search trajectories** during memory recall using hippocampal local field potential signals.
- We hypothesized that this memory process might resemble physical path search strategies such as Lévy flight.

Methods

We acquired hippocampal LFPs from 6 epileptic patients and used a deep learning method to decode the encoded locations and search processes in memory. (Fig 1)

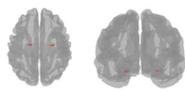


Figure 1. Selected hippocampus channel of subject 1.

We let the patients passively navigate along a circular path in a virtual environment interspersed with 20 equidistant objects and had them perform a recall task in which they had to compare the distance between two choices to a sample shown in the navigated environment. (Fig2)

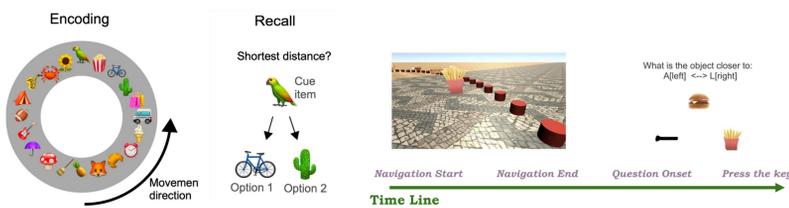


Figure 2. Left: Passive navigation period. Middle: Distance judgement task. Right: Time line of a trial.

Specifically, the model will transform the wide-band neural data into frequency space via a wavelet transformation, which was fed into a convolutional network for training models to reveal behavioral states in the order of millisecond. (Fig3)

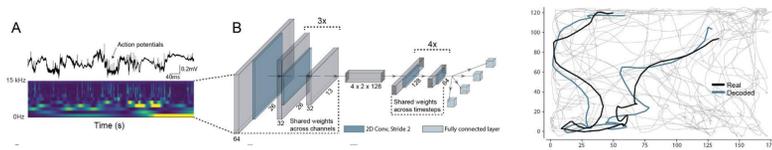
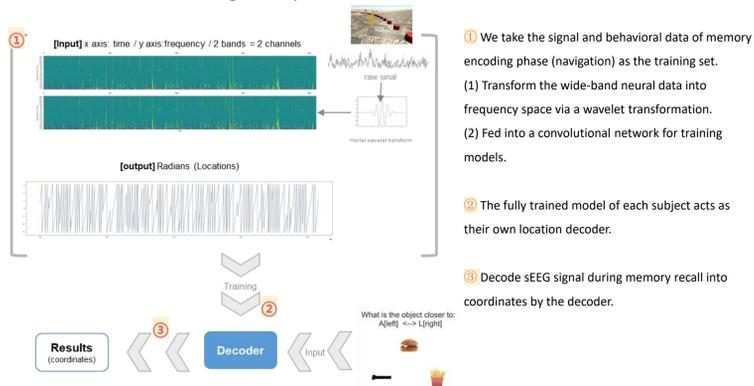
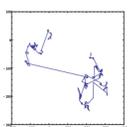


Figure 3. Left: The framework provides a unified way of decoding continuous behaviors or stimuli from neural time-series data. Right: (Frey et al., 2021)

The procedure of decoding and prediction in our real case:



We also fitted the decoded memory search paths with classical Lévy flight distribution $-μ P(l) \sim l$, where $1 < μ < 3$.



The Lévy walk is an optimal searching strategy found widely in nature, from the movement of bacteria to human movements [43–46], especially in foraging strategies. This behavior can be described by

$$P(l) \sim l^{-μ} \text{ with } 1 < μ \leq 3, \quad (7)$$

Results

We produced trial-wise decoded memory search maps within the navigational environment (Fig 4 & 5) and found that the decoded locations reliably predict subject's memory performances. (Fig 6)

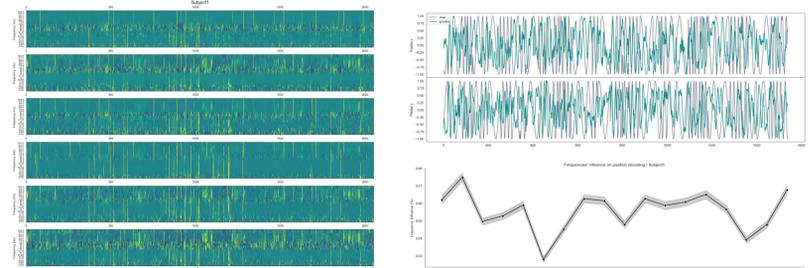


Figure 4. Left: 5 channels' time-frequency plots (wavelet transform) of Subject 1's hippocampal LFP. Right top: Decode performance. Right bottom: Frequency influence calculated by shuffled data.

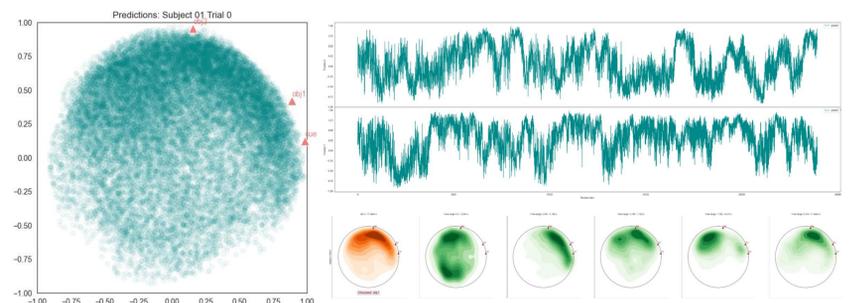


Figure 5. Left: Top view of decoded locations of each sample during question onset to response. Right top: Decoded coordinates of x and y. Right bottom: Kernel density estimation of decoded location (all time - orange / 20% time - green)

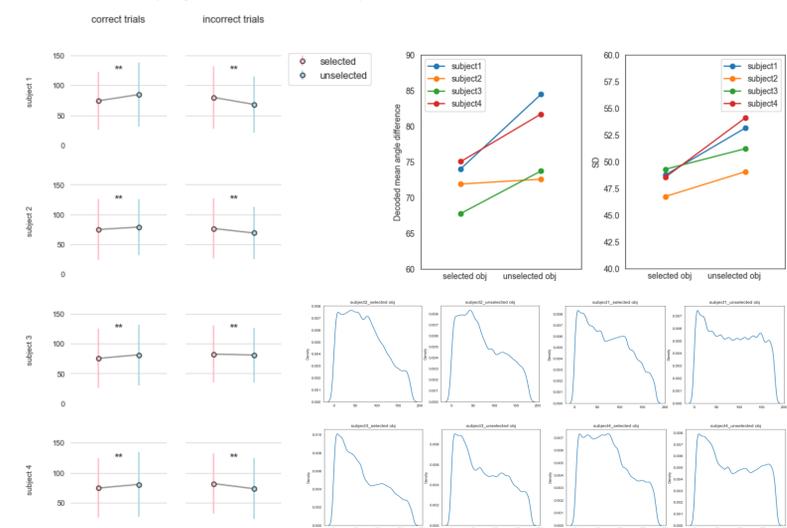


Figure 6. Left: 4 subjects' mean angle difference in correct & in incorrect trials. Right top: Angle difference & SD in correct trials. Right bottom: density plots of 4 subjects. (Mean Angle difference of each subject = $\sum(\text{Angle}_{\text{each sample's decoded location}} - \text{Angle}_{\text{(selected or unselected object)}}) / n_{\text{samples}}$)

Leveraging on the high temporal resolution (0.5 ms / step), we revealed that the memory search trajectory follows a truncated power law, suggesting Lévy flight foraging search in the episodic memory space. (Fig 7)

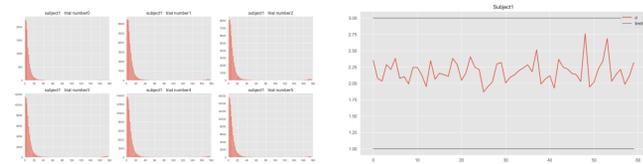


Figure 7. Left: Density plot of subject 1 first 6 trials. Right: Subject 1 all trials' μ . (powerlaw package, Alstott et al, 2014)

Conclusions

Our LFP results delineate a navigational cognitive map in the human hippocampus and made a link between episodic retrieval trajectories in memory space with Lévy foraging phenomenon in physical space.

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